

# ICCAS 2014

## 2nd CALL FOR PAPERS

### 2014 14th International Conference on Control, Automation and Systems

**ICCAS 2014** will be held at KINTEX, Korea on October 22-25, 2014 jointly with Robot World 2014. The aim of the ICCAS is to bring together researchers and engineers worldwide to present their latest works, and disseminate the state-of-the-art technologies related to control, automation, robotics, and systems.

The conference program will include Technical Workshops & Tutorials on Tuesday, October 21. The workshops and tutorials of this year will be specially interesting to those who want to learn about the latest trends and subjects.

**October 22(Wed.)-25(Sat.), 2014**      **KINTEX, Gyeonggi-do, Korea**      <http://2014.iccas.org>

### Paper Submission

You are cordially invited to submit full papers (3 to 6 pages) to <http://2014.iccas.org>. Paper template file can be downloaded from the website. Accepted papers will be published in the ICCAS 2014 Proceedings that will be indexed in IEEE Xplore, SCOPUS and EI compendex, and will be submitted for indexing in Thomson Reuters Conference Proceedings Citation Index (ISI Web of Science).

### Important Dates

- April 4, 2014** : Submission of organized session proposals
- April 18, 2014** **May 2, 2014 (Extended)** : Submission of full papers
- July 11, 2014** : Notification of paper acceptance
- August 11, 2014** : Submission of final camera-ready papers

### Plenary Speakers

					
<b>Frank Allgöwer</b> Univ. of Stuttgart Germany	<b>Harry Asada</b> MIT USA	<b>Lei Guo</b> Chinese Academy of Sciences, China	<b>Homayoon Kazerooni</b> UC Berkeley USA	<b>Min-Jea Tahk</b> KAIST Korea	<b>Yutaka Yamamoto</b> Kyoto University Japan

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# ICCRAS 2014

Topics of the conference include but are not limited to

## Control Theory and Applications

Linear/Nonlinear Control  
Adaptive/Robust Control  
Identification and Estimation

## Control Devices and Instruments

Power Electronics  
Hydraulic/Pneumatic Systems  
MEMS and Nano Technologies

## Industrial Applications of Control

Automotive Systems  
Power Systems  
Communication Systems  
Manufacturing Systems and Automation

## Sensors and Signal Processing

Sensors and Instrumentation  
Signal Processing and Sensor Fusion  
Fault Diagnosis

## Intelligent Systems

Artificial Neural Networks  
Fuzzy Systems

## Robot Mechanism and Control

Kinematics and Dynamics of Robots  
Manipulation and Motion Planning  
Mobile Robots and Navigation

## Robot Vision

Robot Vision and Visual Servoing  
Object/Human Visual Recognition

## Human-Robot Interaction

Human-Robot Interaction  
Speech Recognition  
Haptics and Virtual Presence  
Virtual Reality based Simulation

## Robotic Applications

Biorobotics and Medical Robots  
Service and Field Robots  
Humanoid Robots  
Automations

## Unmanned Vehicle Systems

Unmanned Aerial Vehicles  
Unmanned Ground Vehicles  
Unmanned Underwater Vehicles

## Navigation, Guidance and Control

Navigation Algorithms  
Guidance Technologies  
GPS

## Process Systems

Process Control and Monitoring  
Process Design and Optimization  
Process Automation

## Biomedical Systems

Biomedical Instrumentation  
Biomedical Signal Processing  
Bio-Systems and Control

## Information and Networking

Real-Time and Embedded Systems  
Network-Based Control Systems  
Networked/Ambient Intelligence

## Multimedia Systems

Database and Data Fusion  
Computer Animation

## Civil and Urban Systems

Environmental Engineering  
Structural Control and Health Monitoring  
Smart Structures

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## Special Sessions Provided by KEIT (Korea Evaluation Institute of Industrial Technology)

Three successful selective cases of robot-related R&D projects funded by the Korean Government will be presented together with the robot R&D roadmap.

